## Evaluation ONLINE LEARNING LINKS WITH OPTIMIZATION AND GAMES UNIVERSITÉ PARIS–SACLAY

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## ALTERNATIVES TO FTRL AND FTL

In the context of online convex optimization with differentiable losses, let H be a mirror map compatible with  $\mathscr{X}, x_0 \in \mathscr{X} \cap$  int dom H and consider

$$x_{t+1} = \operatorname*{argmin}_{x \in \mathscr{X}} \left\{ \langle \nabla \ell_t(x_t), x \rangle + \sum_{s=0}^t \mathcal{D}_{\ell_s}(x, x_t) + \mathcal{D}_{\mathcal{H}}(x, x_t) \right\}.$$

- 1) Prove that the above can be interpreted as UMD iterates.
- 2) Derive a regret bound (on  $\sum_{t=0}^{T} (\ell_t(x_t) \ell_t(x)))$  and compare with the corresponding regret bound for FTRL.
- 3) Generalize with a sequence of time-dependent mirror maps  $(H_t)_{t \ge 0}$  and derive similar results as for FTRL.
- 4) In the case of differentiable strongly convex losses, consider

$$x_{t+1} = \operatorname*{argmin}_{x \in \mathscr{X}} \left\{ \langle 
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angle + \sum_{s=0}^t \mathcal{D}_{\ell_s}(x, x_t) 
ight\},$$

and derive regret guarantees.

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